

# Voronoi Tessellations for Ocean Modeling: Methods, Modes, and Conservation

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# Scope

1. Voronoi tessellations and their properties
2. Low (2nd-order) finite-volume methods
3. Structured and unstructured meshes
4. Shallow-water equations / layered OGCM

# Outline

1. Definition of a Voronoi Tessellation (VT)
2. Definition of a Centroidal VT -- a special class
3. Discretization -- so many choices
4. Modes and Euler's Formula
5. Mimetic methods -- a route to conservation
6. Structured vs. Unstructured VTs
7. My views on where this all is heading

Nearly everything here is applicable to any mesh using FV methods.

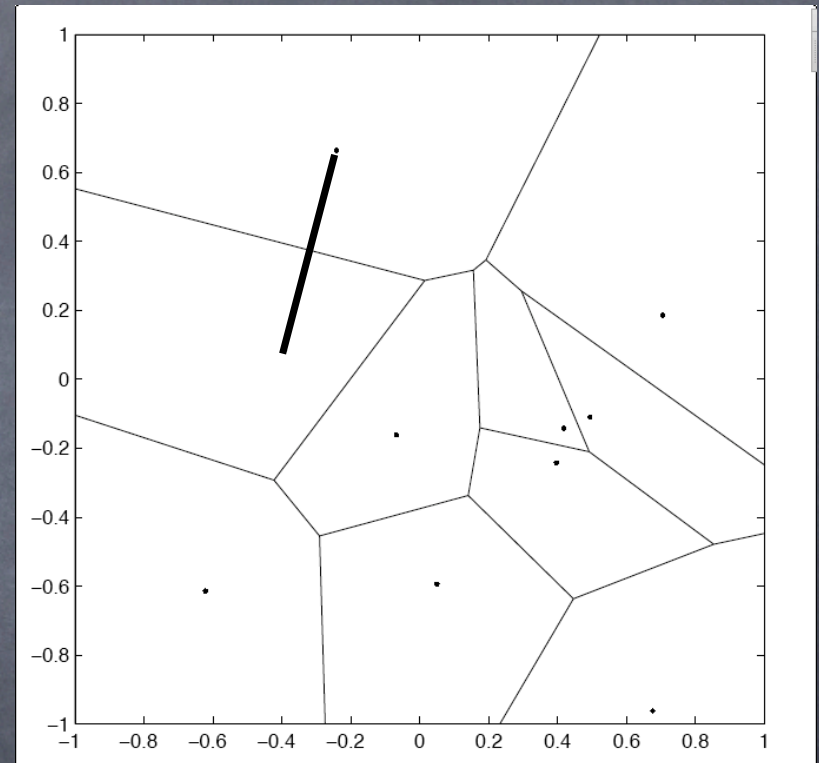
# Definition of a Voronoi Tessellations

Given a region,  $S$

And a set of generators,  $z_i \dots$

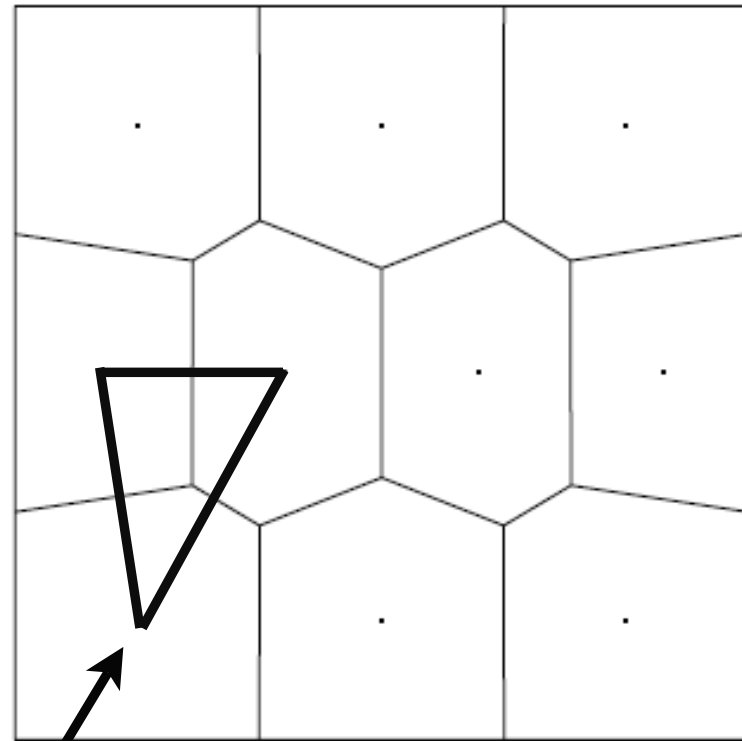
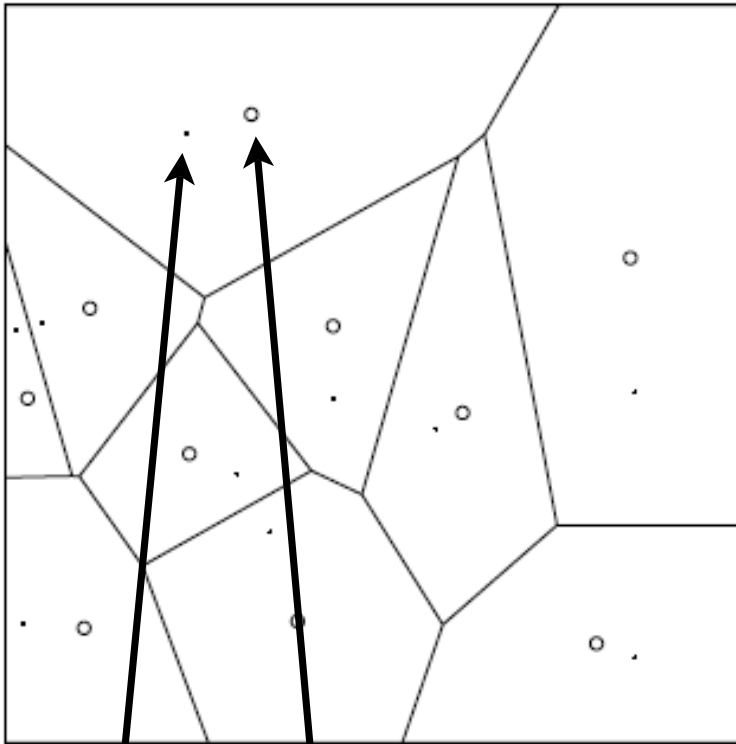
The Voronoi region,  $V_i$ , for each  $z_i$  is the set of all points closer to  $z_i$  than  $z_j$  for  $j$  not equal to  $i$ .

We are guaranteed that the line connecting generators is orthogonal to the shared edge and is bisected by that edge.



But this does not mean that the grid is nice ....

# Definition of a Centroidal Voronoi Tessellations



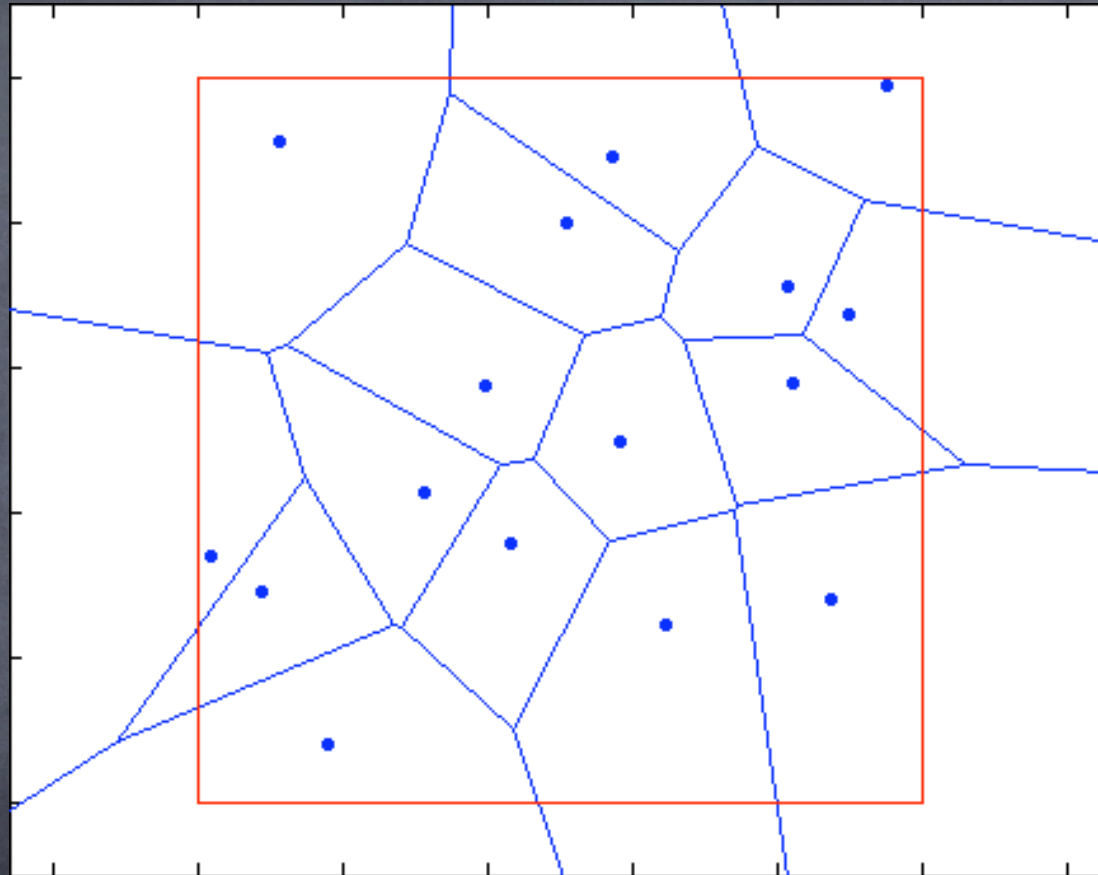
Dual tessellation

$z_i$

$z_i^*$  = center of mass wrt  
a user-defined density function

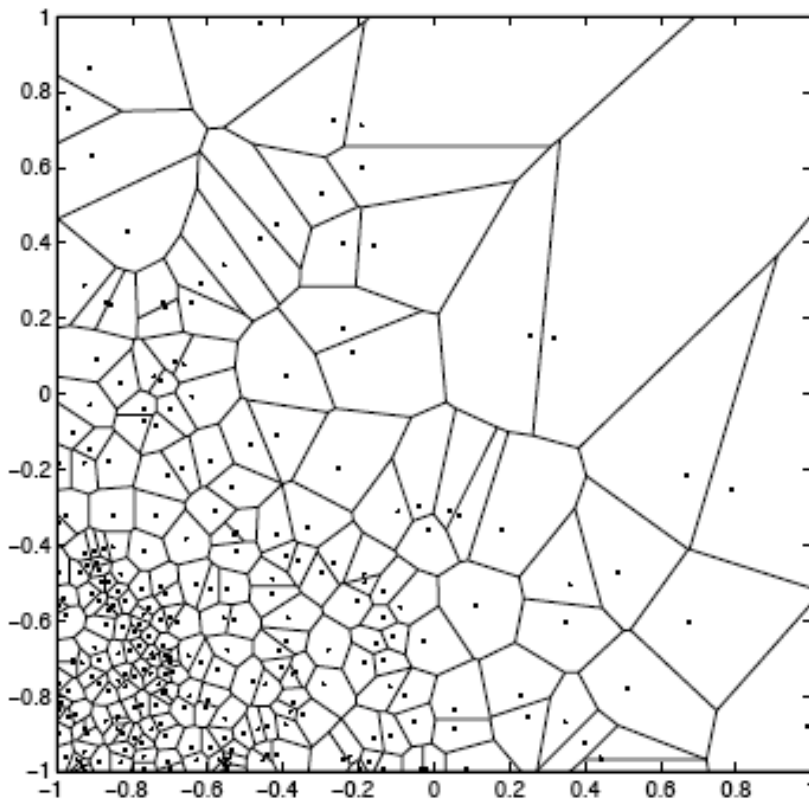
$$z^* = \frac{\int_V w \rho(w) dw}{\int_V \rho(w) dw}$$

# Iterating toward and CVT ....

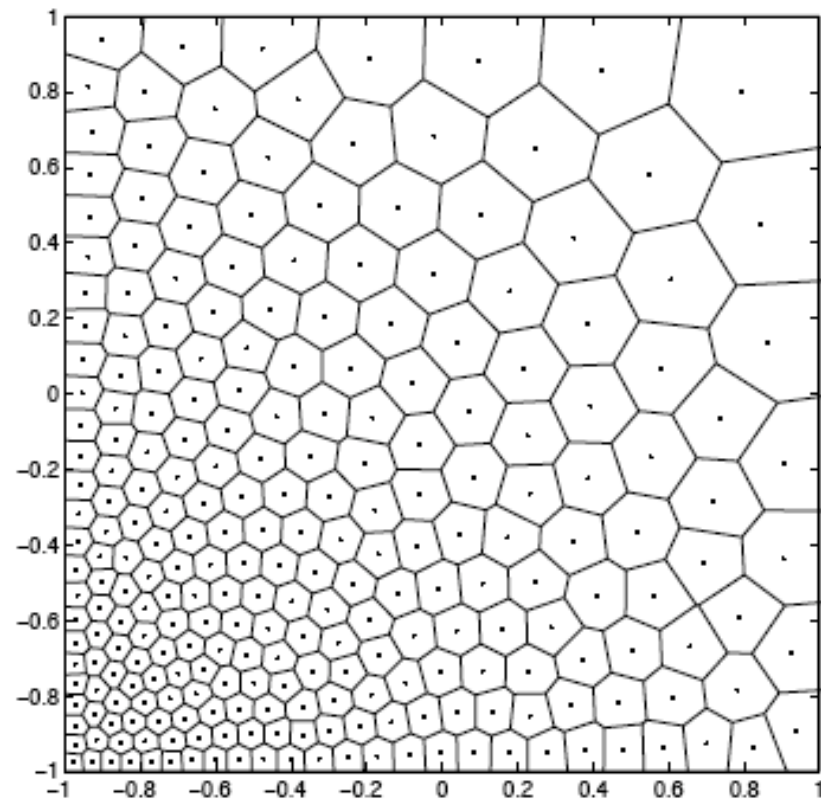


# Non-uniform Centroidal Voronoi Tessellations

Distribute generators in such a way as to make the grid regular.  
Also biases the location of those generators to regions of high density.



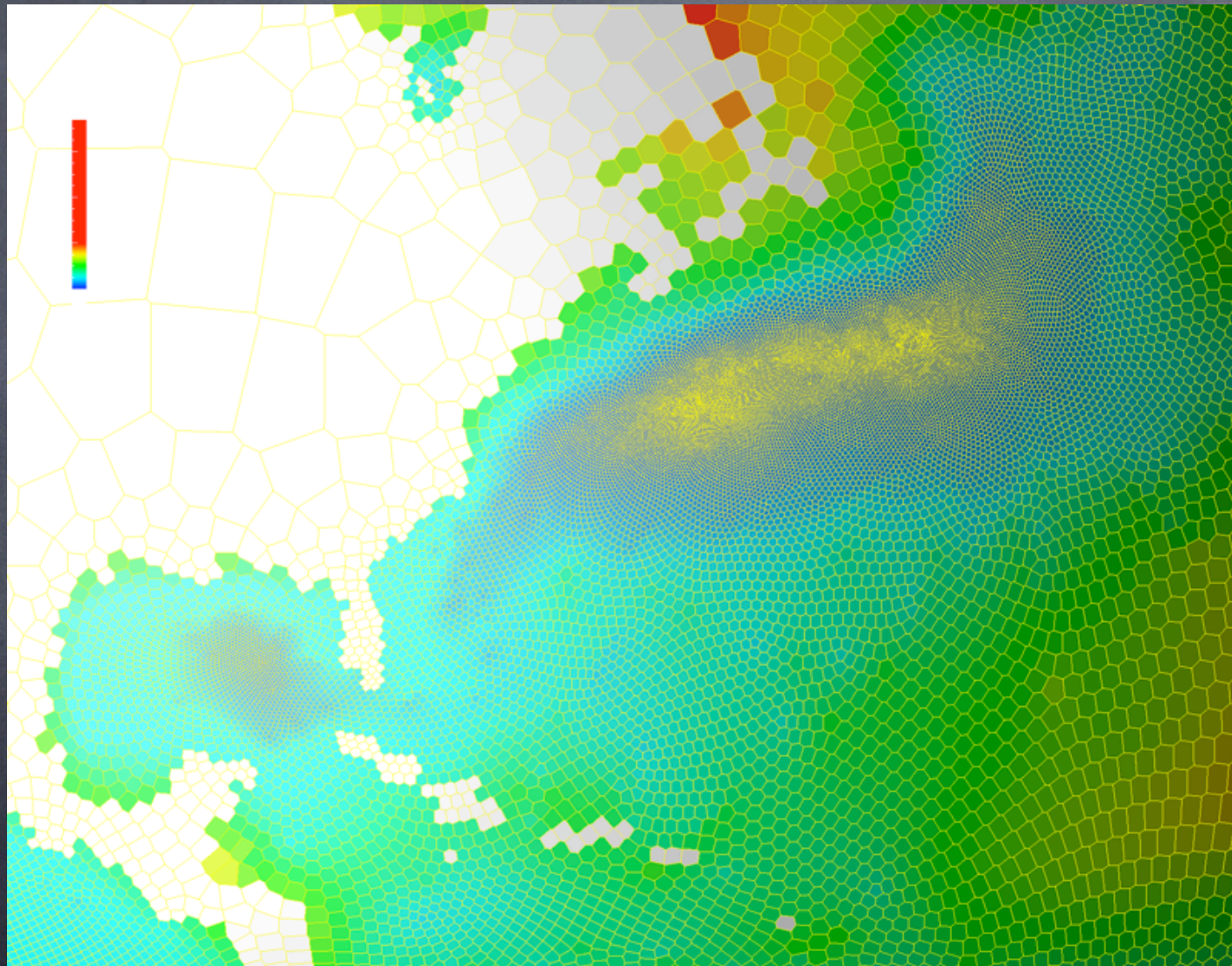
Random sampling



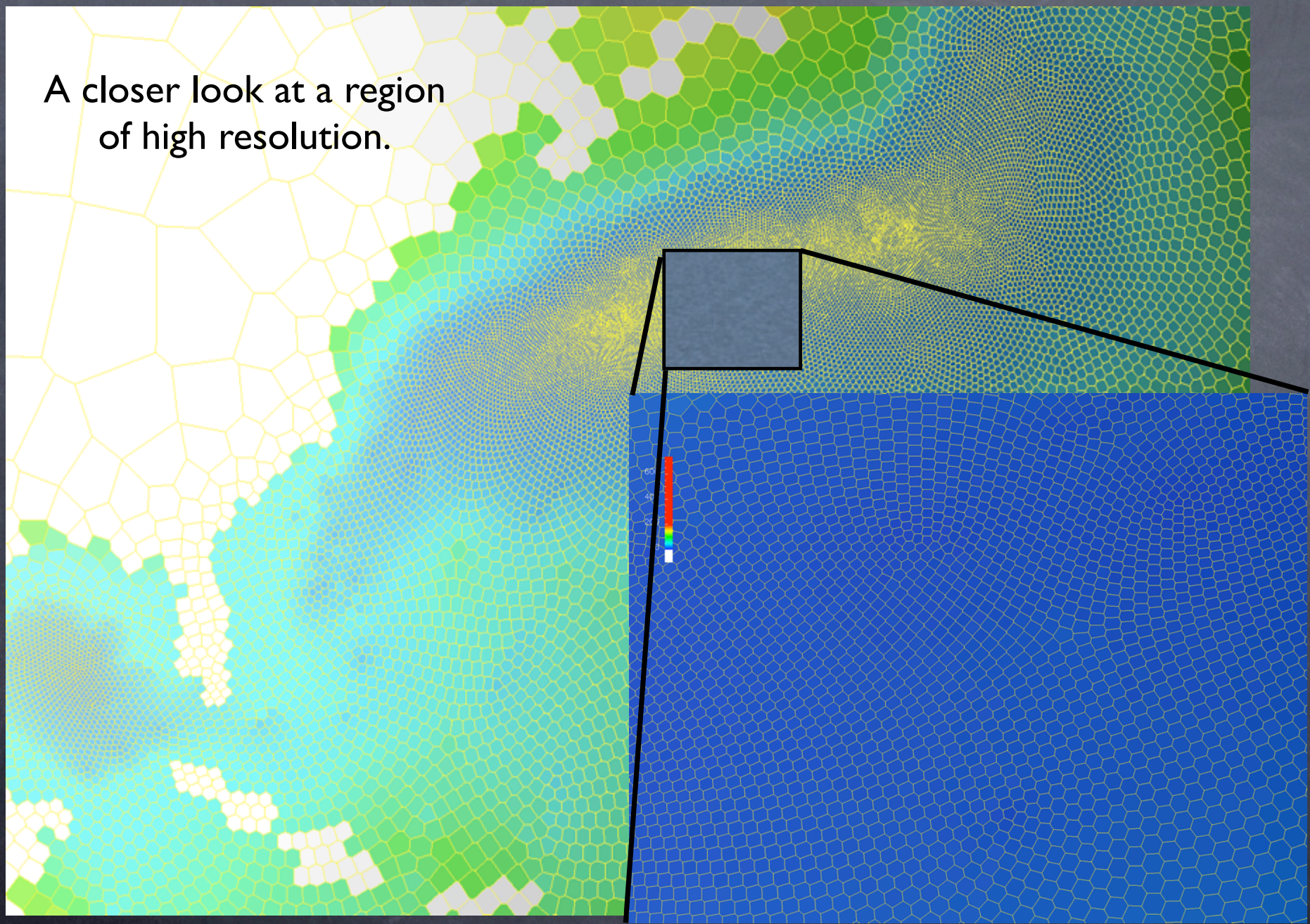
Centroidal Voronoi

# An example of an SCVT

the density proxy use here was TOPEX SSH Variance



A closer look at a region  
of high resolution.



## (S)CVTs have their roots in applied math ...

Gersho conjecture (now proven in 2D): as we added generators, all cells evolve toward perfect hexagons. Meaning that the grid just keeps getting more regular as we add resolution.

Optimal sampling: given a region,  $R$ , and  $N$  buckets to measure precipitation in  $R$ , the optimal placement of those buckets is a CVT. If a prior distribution,  $P$ , of precipitation is known, the CVT takes that information into account with  $\rho = P^{1/2}$ .

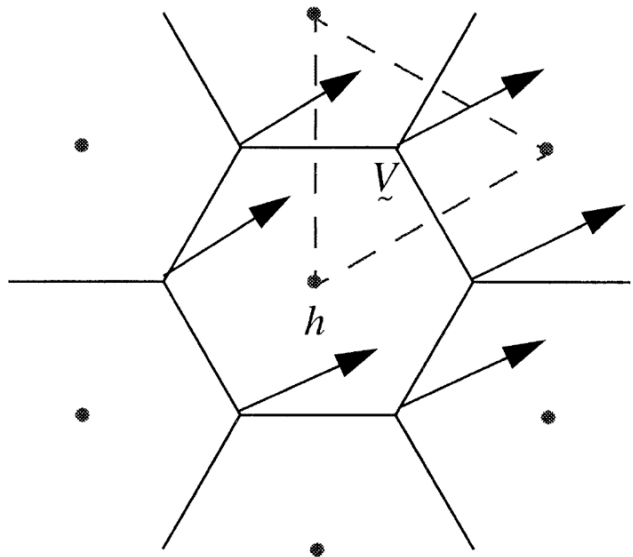
Guaranteed to have 2nd-order truncation error of Poisson equation.

In summary: if Voronoi tessellations are to be used, then there is no good reason not to use Centroidal Voronoi Tessellations.

A mesh without robust numerical methods  
is useless, so what about discretization?

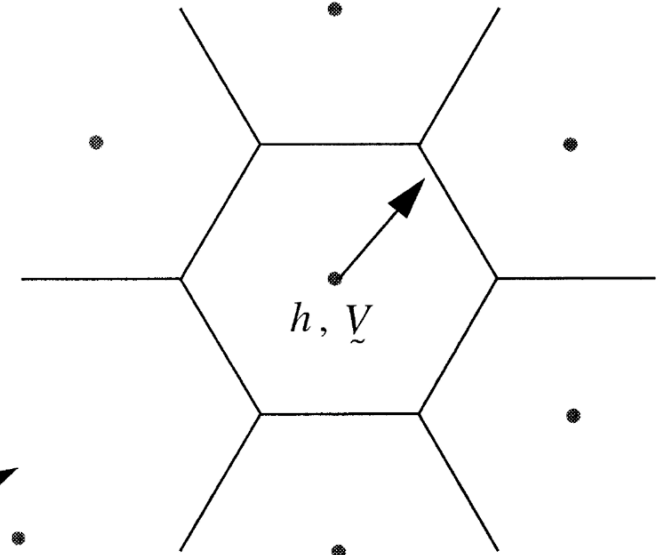
# Some grid-staggering options ...

ZM-grid



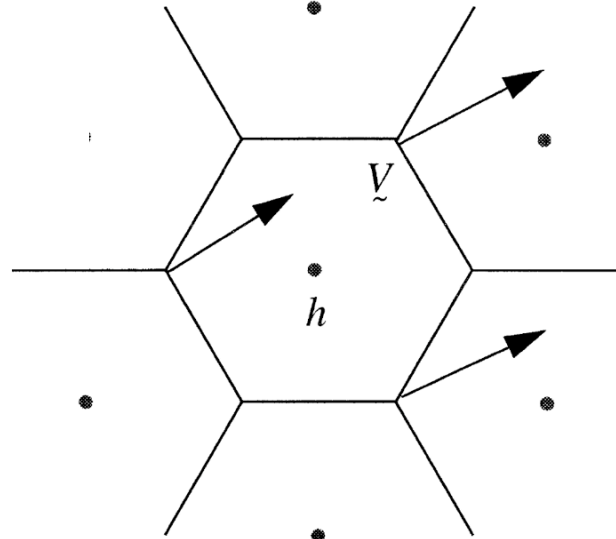
CSU Ocean  
Model

HA-grid

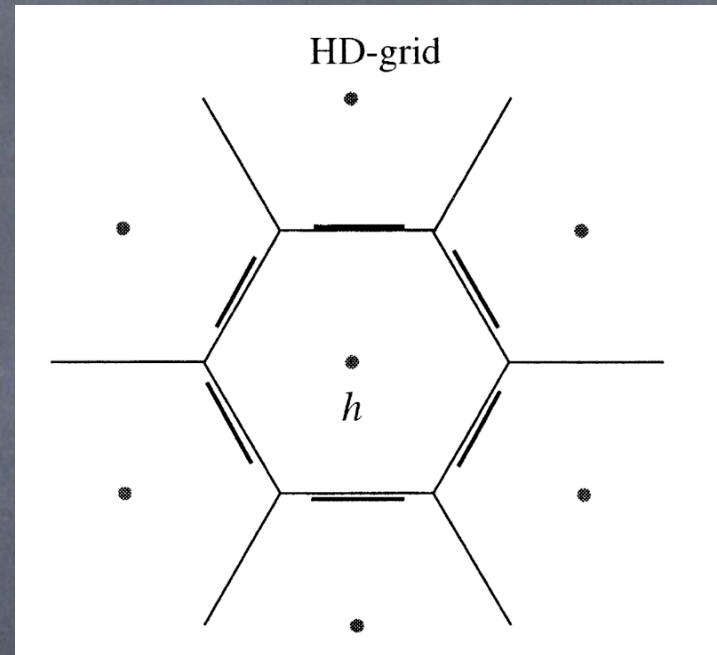
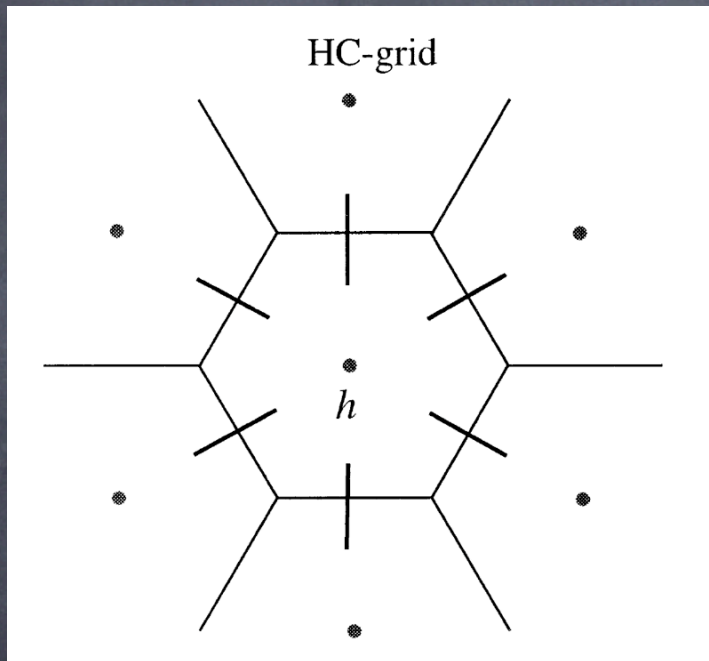


Frontier  
AGCM

HB-grid

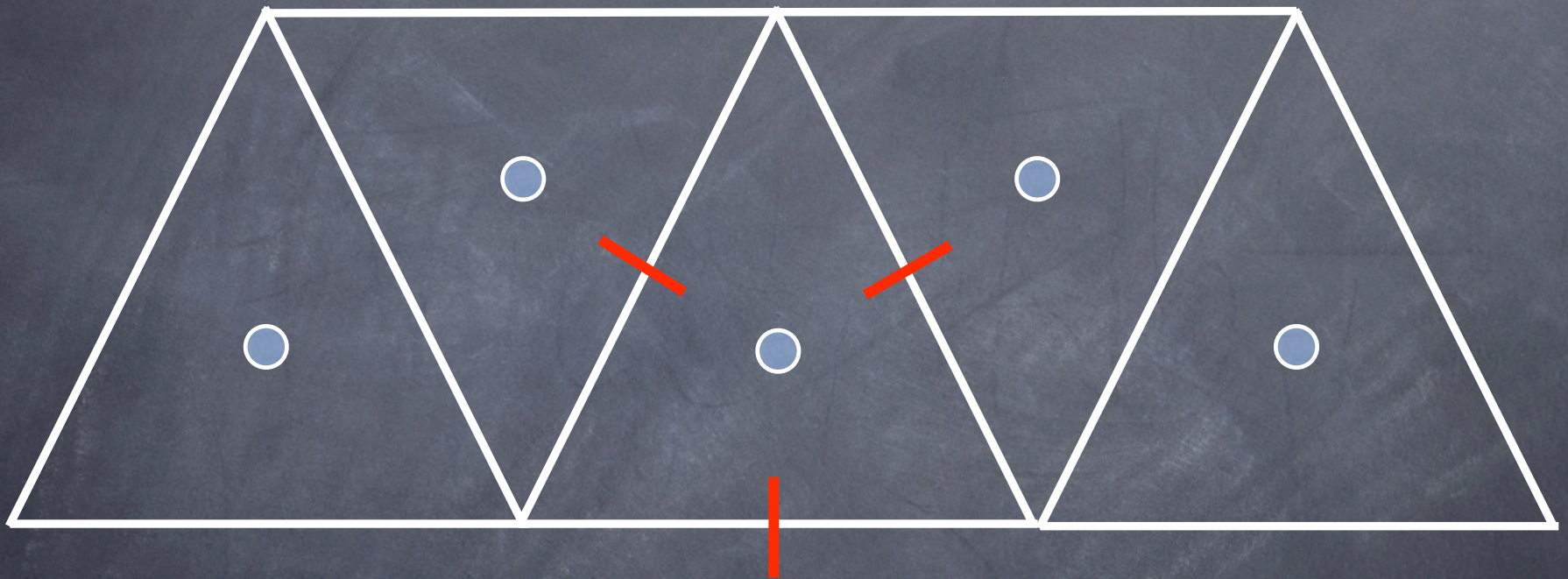


and more options ...



A staggering we are going to consider for our variable resolution grids.

and for those who prefer the dual  
tessellation of triangles ...



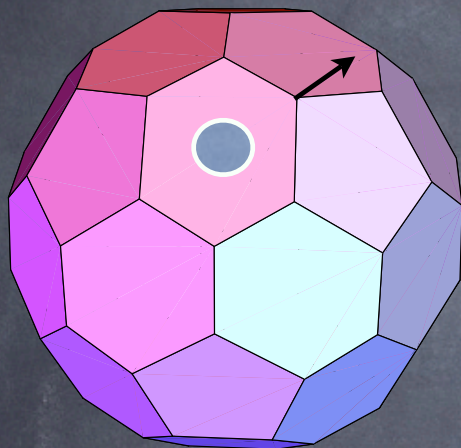
MPI/DWD ICON project

# So with so many options, how do we go about choosing the correct grid staggering?

1. Many (by not all) of the known characteristics of quad-staggerings carry over.
2. Detailed look at the linear geostrophic adjustment problem, i.e. gravity waves, geostrophic balance, and (most importantly) null spaces.
3. Detailed look at nonlinear properties, such as energy and potential enstrophy (conservation or boundedness).

# Euler's Formula and Free Modes

$$\text{Faces} + \text{Vertices} - \text{Edges} = 2$$



Faces = 42  $\longrightarrow$  mass

Vertices = 80  $\longrightarrow$  velocity

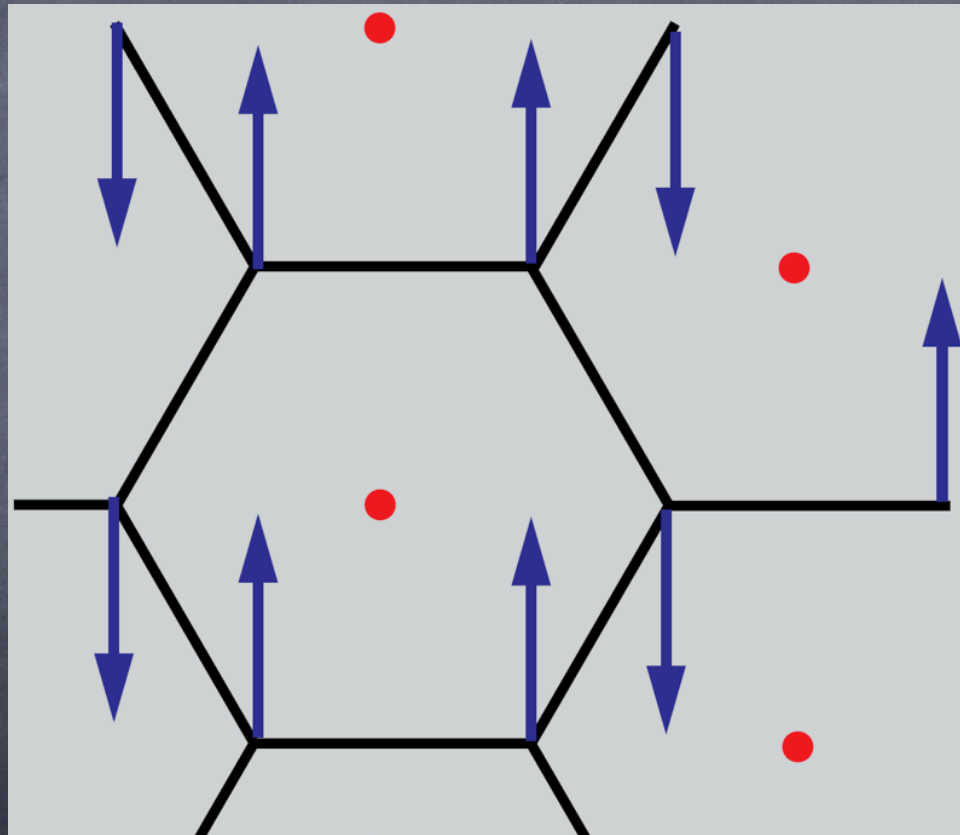
Edges = 120

The continuous shallow-water equations have one full (2d) vector associated with each mass.

80 velocity modes - 42 mass modes = 38 free velocity modes.

Susceptible to grid-scale noise in velocity field.

In this system, the extra velocity modes create patterns with zero div and zero curl.

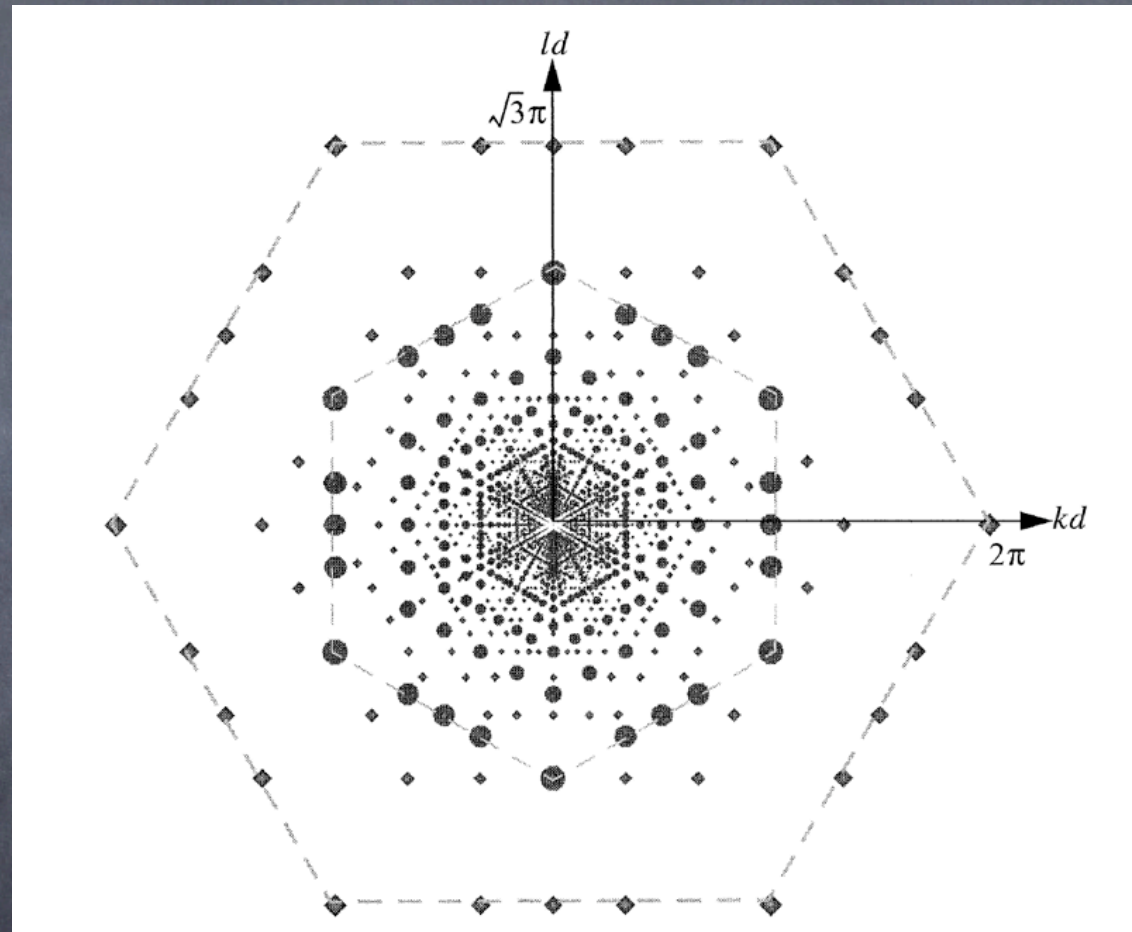


# A full analysis of the discrete modes

Circles depict mass modes.

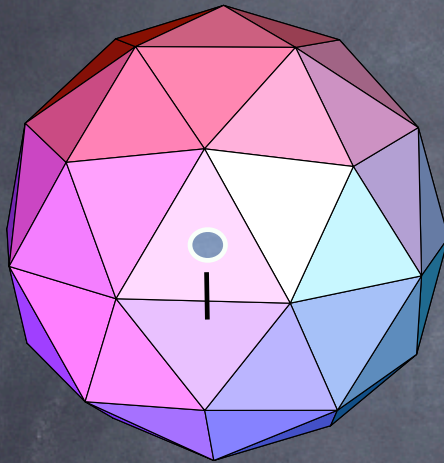
Diamonds depict velocity modes.

In terms of vorticity and divergence, the region between the hexagons is aliased into the inner hexagon.



# What about the triangular C-grid?

$$\text{Faces} + \text{Vertices} - \text{Edges} = 2$$



Faces = 80  $\longrightarrow$  mass

Vertices = 42

Edges = 120  $\longrightarrow$  velocity (1/2)

80 mass modes - 60 velocity modes = 20 free mass modes.

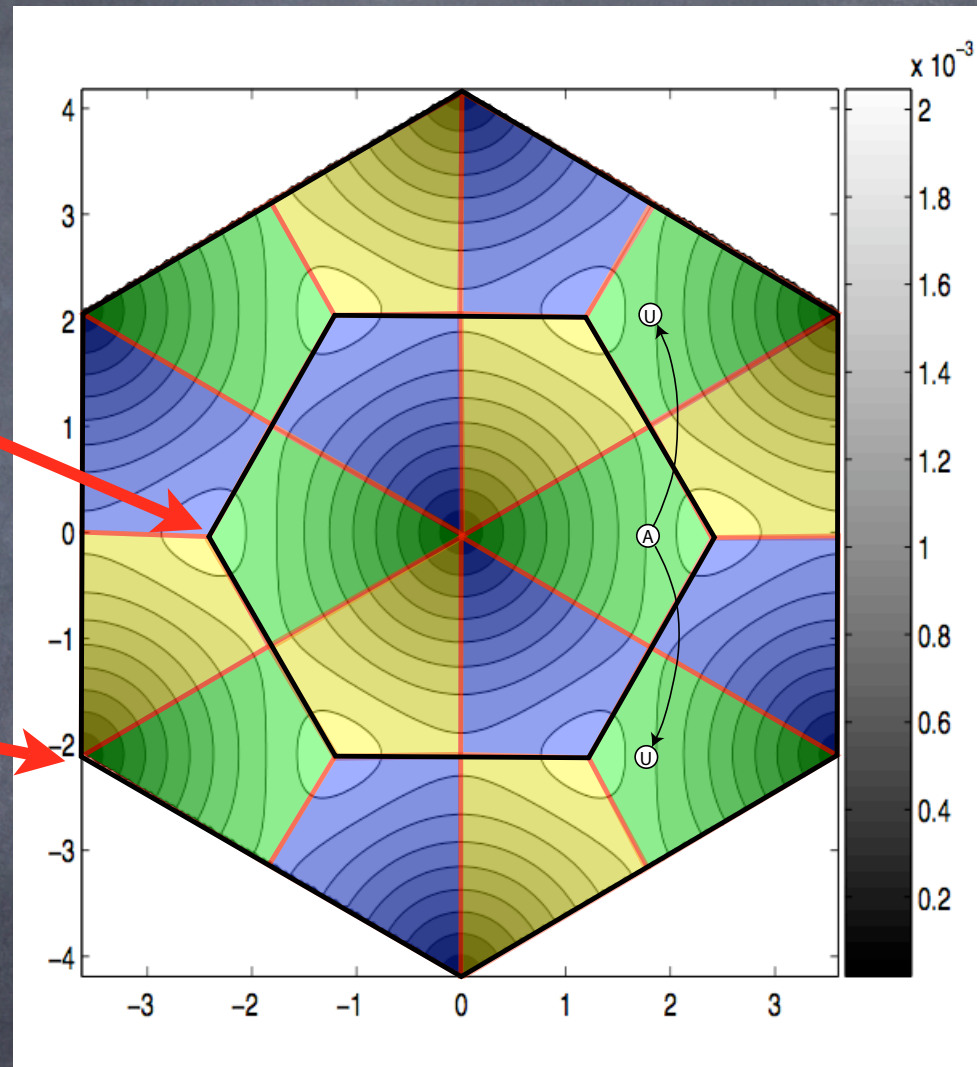
Susceptible to grid-scale noise in mass field.

# Dispersion relation on triangular C-grid

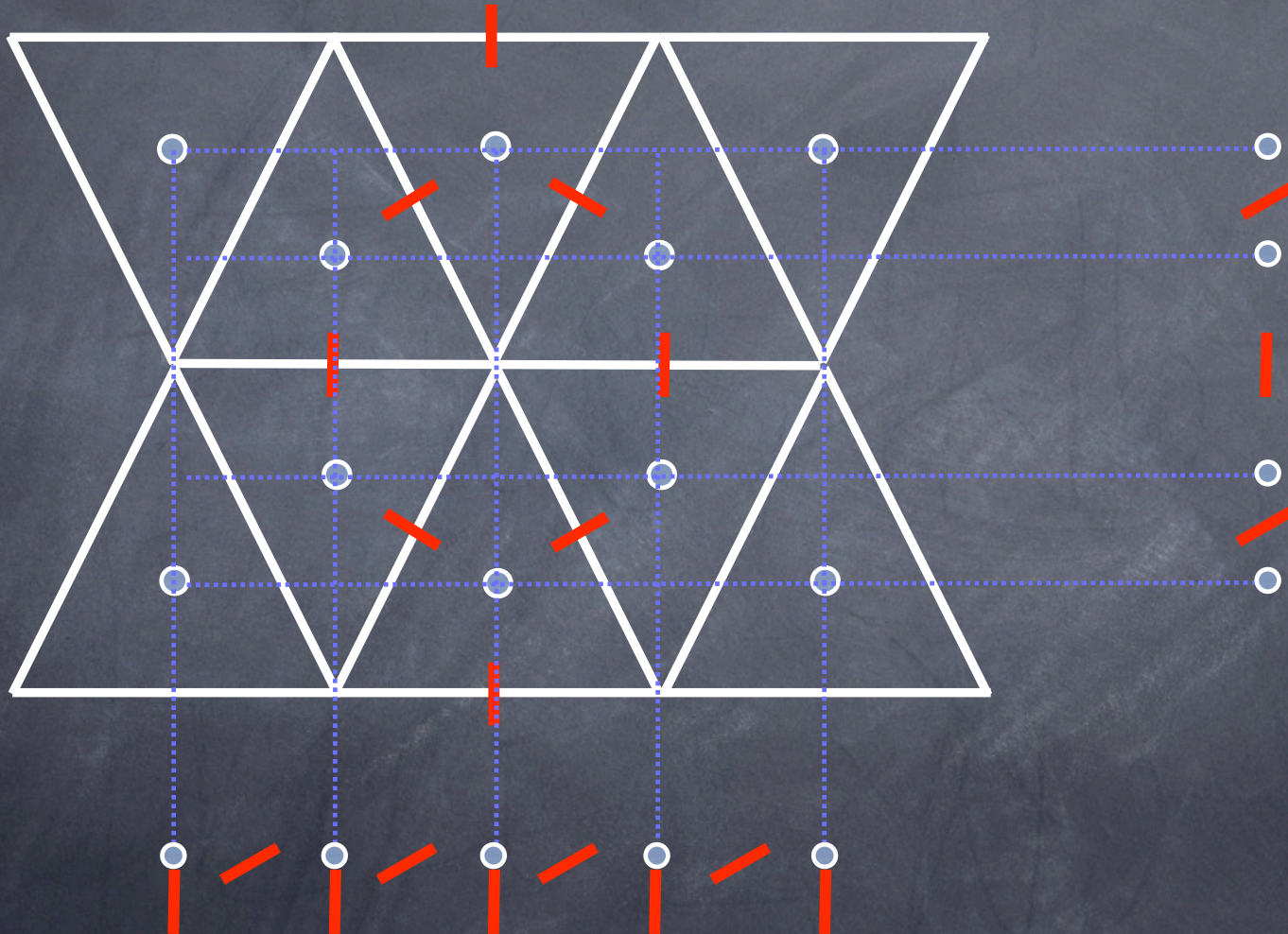
Asymmetry in relation

zero group velocity locations

zero phase velocity locations



Collapse grid in each direction:  
grid works different in x and y



Unconstrained modes are always going to be an issue on these grids. The solution is to identify them early, determine their severity, and develop stencils to suppress/filter these modes.

# Mimetic Methods:

The idea probably has merit, it has been “invented” in at least three different lines of work.

Developing discrete analogs to the weak-form definitions of div, grad, and curl such that certain vector identities hold exactly.

These vector identities are a necessary prerequisite for energy conservation. At a minimum, these vector identities lead to a coherent formulation.

Robust, extensible method applicable to any FV grid.

# Building operators from line integrals

$$\text{grad}(h) = \nabla h = \lim_{A \rightarrow 0} \frac{1}{A} \int_c h \tilde{n} dl$$

$$\text{div}(\tilde{V}) = \nabla \cdot \tilde{V} = \lim_{A \rightarrow 0} \frac{1}{A} \int_c \tilde{V} \cdot \tilde{n} dl$$

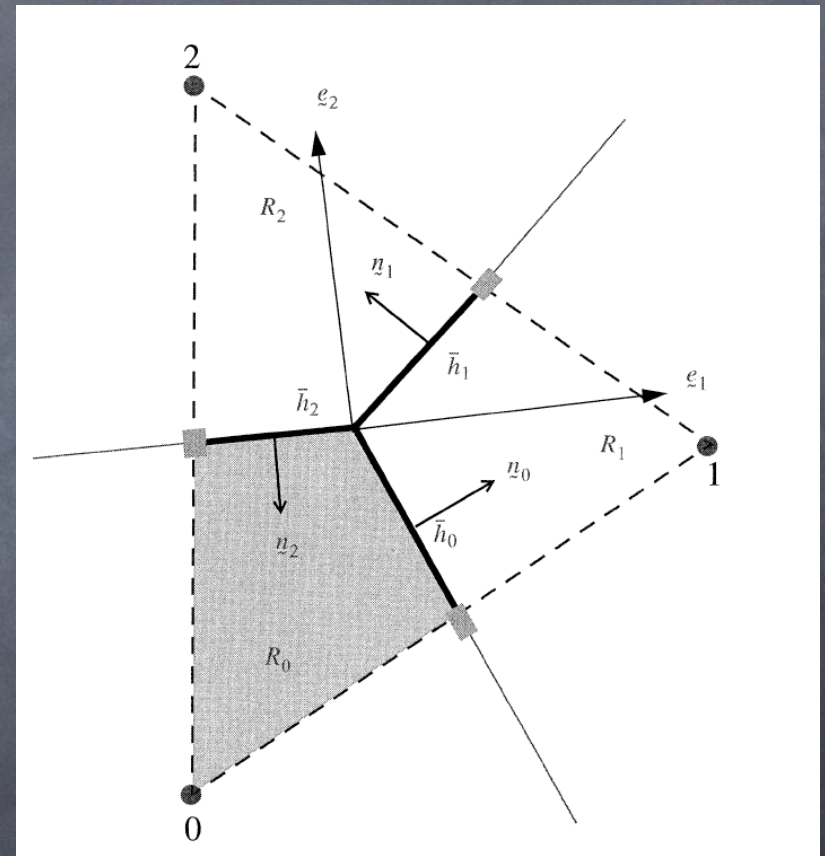


$$\nabla \cdot (h \tilde{V}) = h \nabla \cdot \tilde{V} + \tilde{V} \cdot \nabla h$$

$$\tilde{\sigma} : \nabla \tilde{V} + \tilde{V} \cdot (\nabla \cdot \tilde{\sigma}) = 0$$

heating in internal energy  
(positive definite)

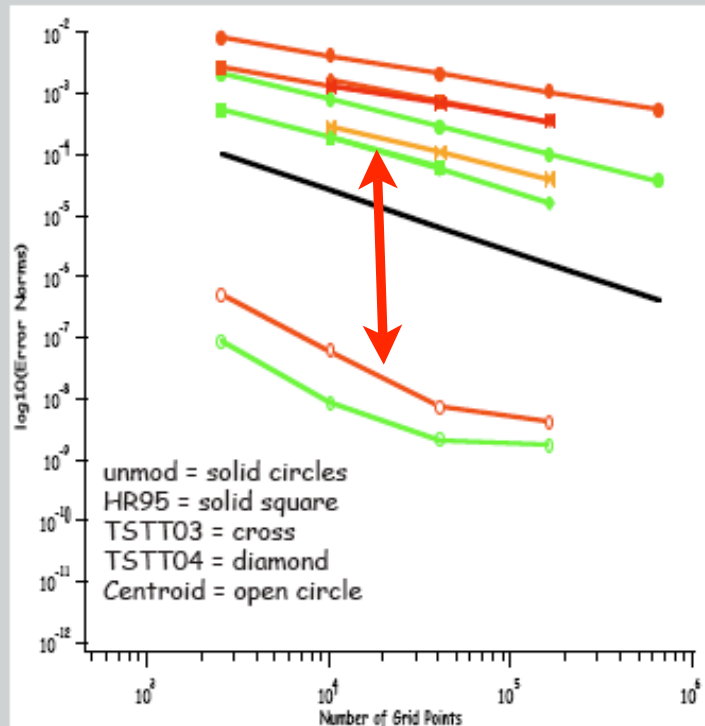
dissipation in momentum  
(negative definite)



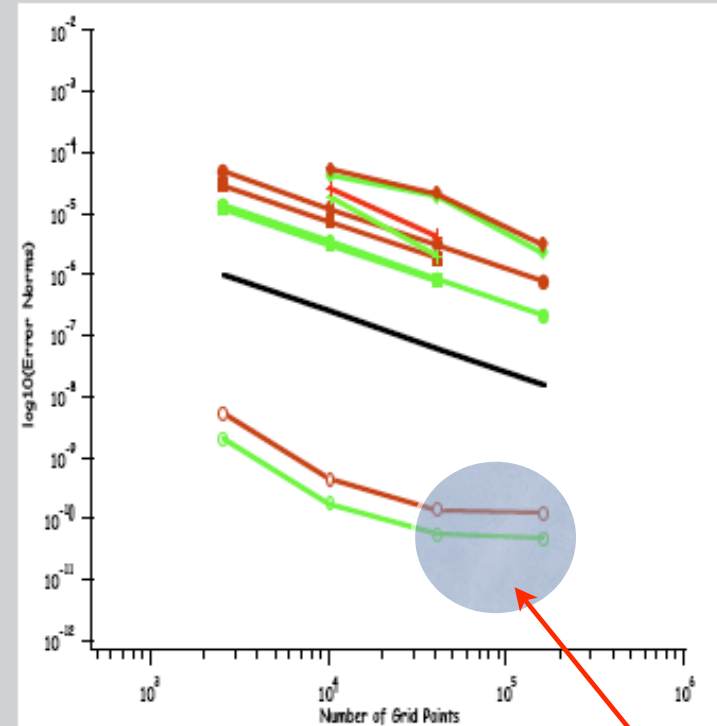
# The accuracy of these operators ... looking at the Laplacian

**Solution#1:**  $u = \sin \phi$

Truncation Error  
L2 Norm in Green, Linf Norm in Red  
Black Line indicates -2 convergence



Solution Error  
L2 Norm in Green, Linf Norm in Red  
Black Line indicates -2 convergence



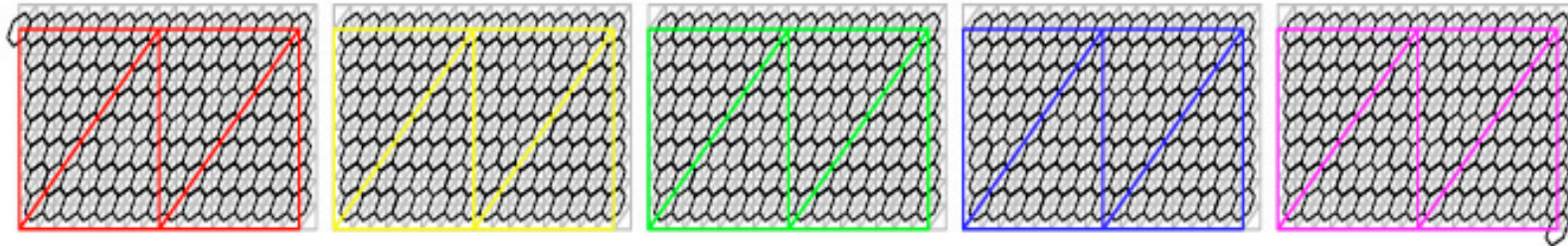
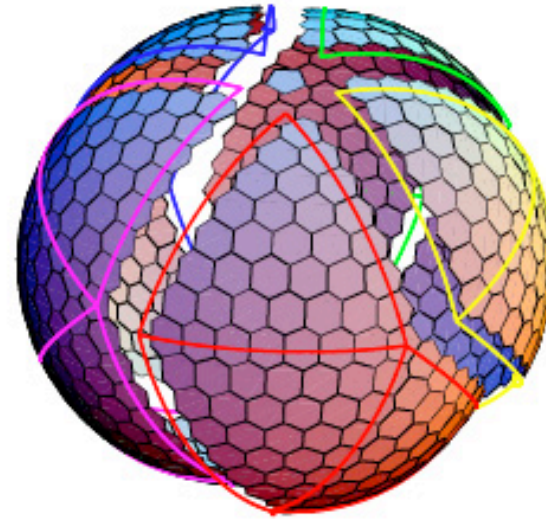
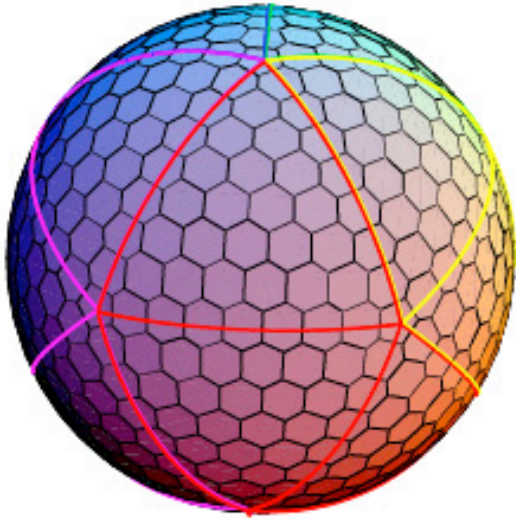
spread is  
due to the  
use of a  
spherical  
harmonic  
as the test  
function

round-off

The mimetic approach provides robust analogs to discrete vector identities with second-order accuracy in the solution error.

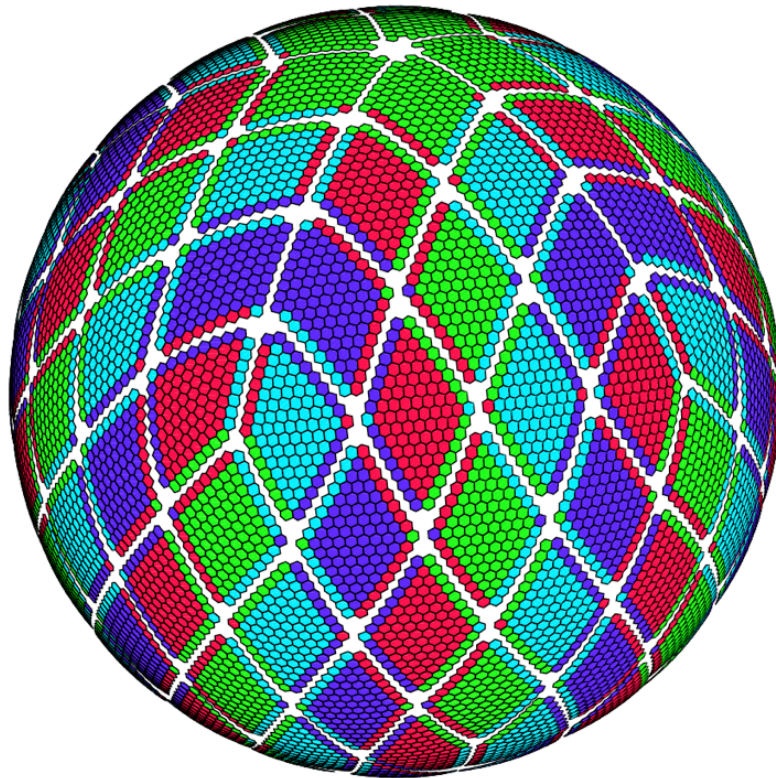
Making a model that scales ...  
the trade-off between structured  
and unstructured meshes.

# Voronoi Tessellations: Structured Meshes



structured topology breaks down for even mildly varying resolutions.

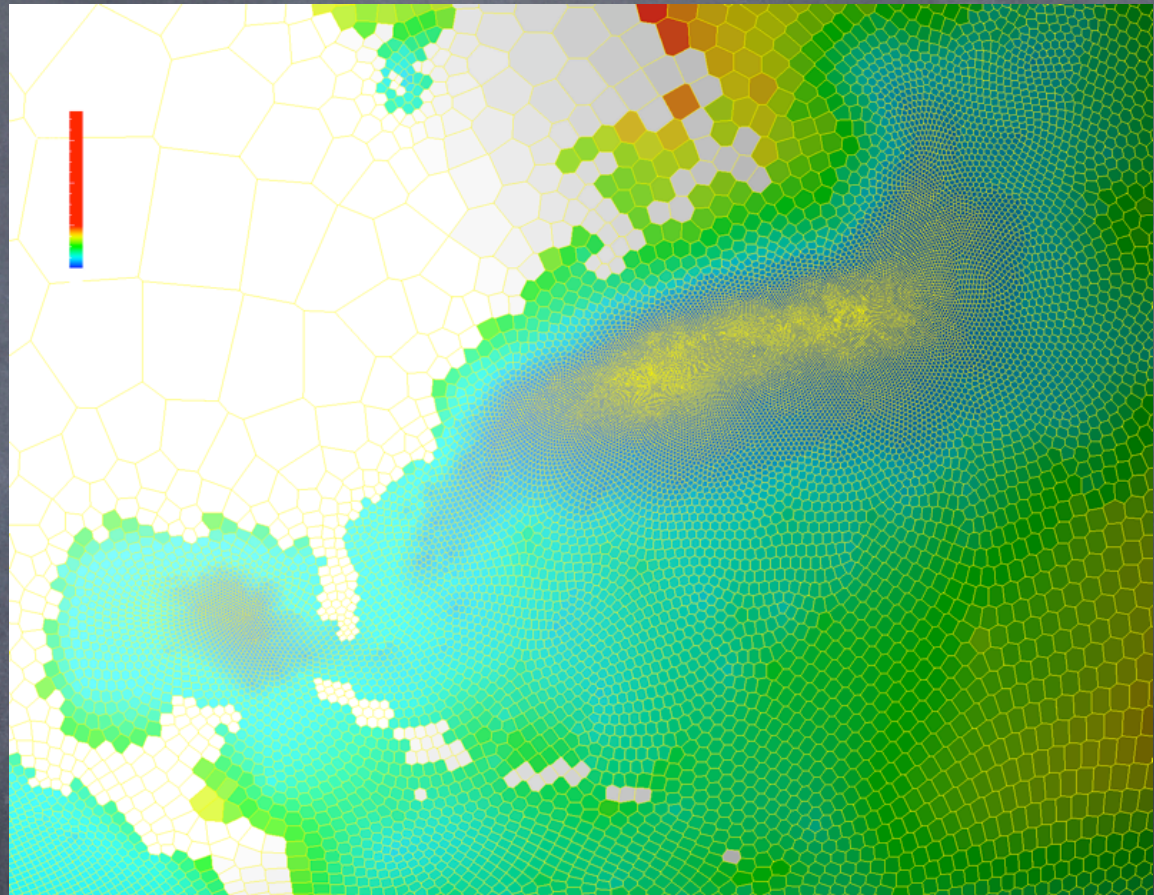
# Voronoi Tessellations: Blocks for Domain Decomposition for structured meshes



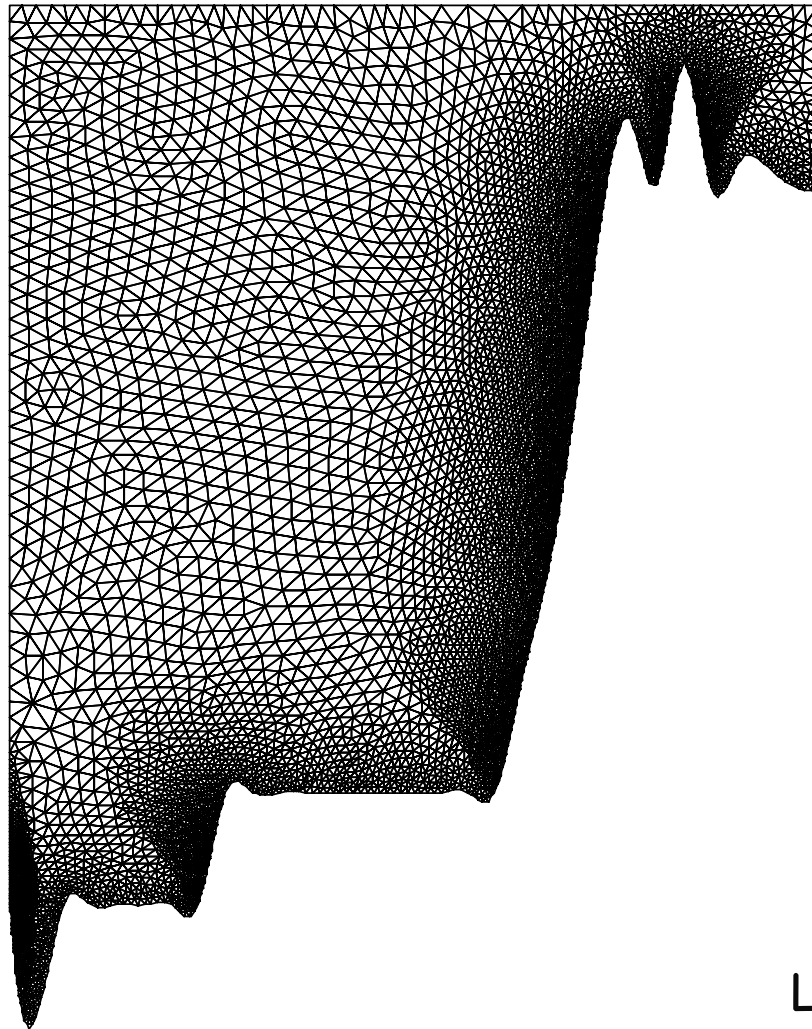
# Unstructured mesh ...

really no different  
than a finite-element  
mesh.

indirect addressing  
is required, i.e. my  
neighbor to the right  
is not at  $i+1$



# Unstructured 3D meshes ... testing the idea in x-z



Lili Ju

# Degrees of freedom and scaling ...

$$C \approx \alpha^D$$

where  $C$  is the cost  
 $\alpha$  is the scaling factor (min/max)  
and  $D$  is the dimension.

for an  $\alpha$  of .2, the cost goes as  
.2, .04, .008 for  $D=1,2,3$ .

# The trade-offs

## Structured meshes

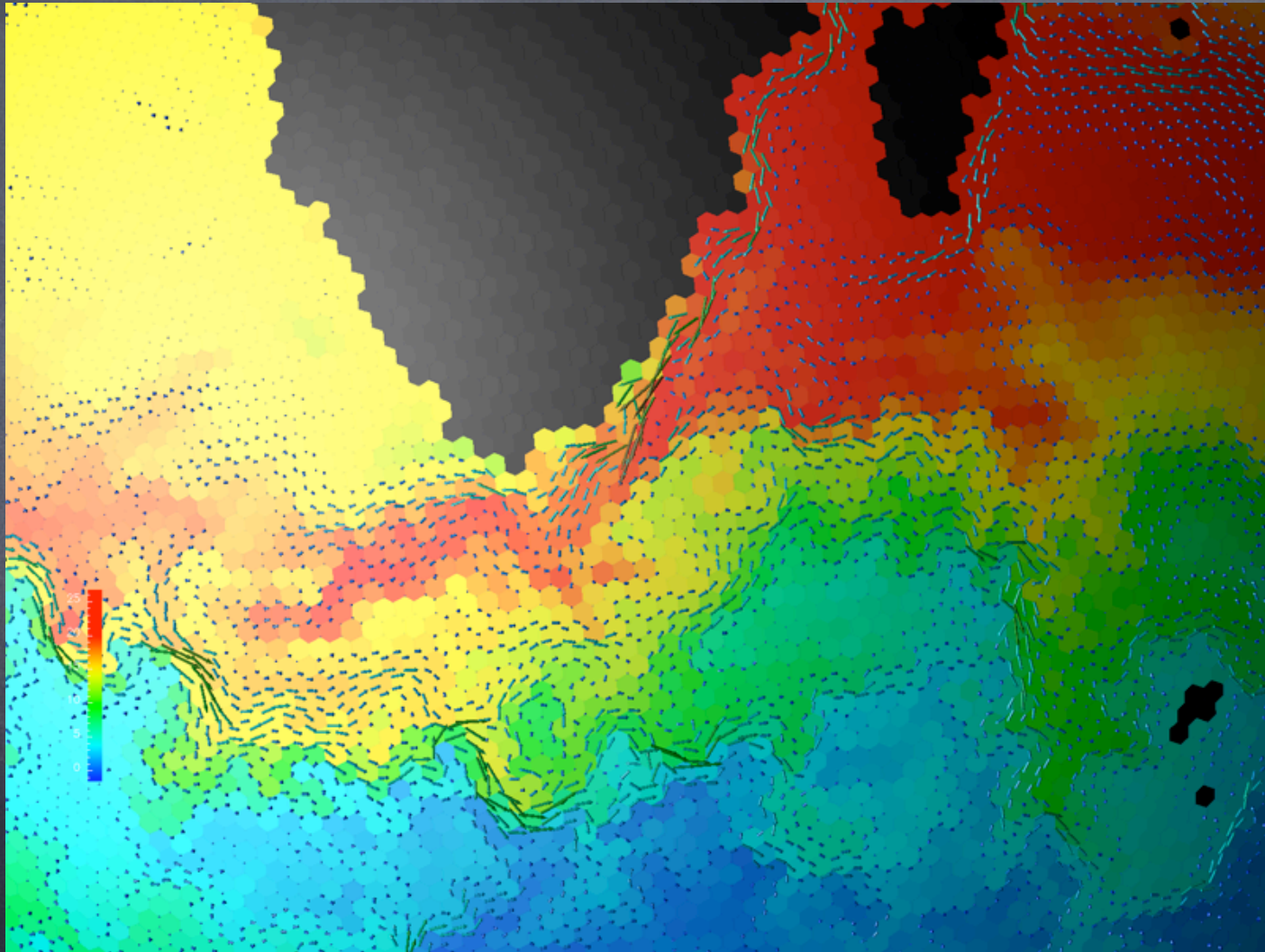
- computationally efficient
- quasi-uniform meshes only option
- regional domains possible, but cumbersome

## Unstructured meshes

- computationally challenging
- efficient allocation of resources (if we know where to put them)
- regional domains possible
- flexible and adaptive

Where is this all heading?

Voronoi Tessellations are viable,  
the question is are they better?



# My very personal perspective

#1: Quasi-uniform Voronoi tessellations could be as useful as the traditional quadrilateral grids, given a commensurate effort as quads.

#2: If we think that non-uniform grids are potentially useful to global ocean modeling, then centroidal Voronoi tessellations are compelling.

